Executive Summary

I am a Principal Engineer with 12 years of experience in embedded systems, IoT, and autonomous vehicle technologies, with a strong track record of technical leadership and project management in European and national research projects. My expertise spans the full innovation cycle, proposal development, system architecture, hands-on prototyping, integration, and deployment of advanced solutions for mobility, energy, and smart infrastructure.

My engineering foundation encompasses in-depth knowledge of Vehicle-to-everything (V2X) communications, sensor integration, real-time embedded software, and system-level design, complemented by practical experience in C, C++, Python, PCB design, and Linux-based development. I am committed to continuous professional growth, including formal training in deep learning and autonomous systems, to remain at the forefront of technology and innovation management.

As Principal Engineer of AUTONAVIS R&D, I have overseen all phases of innovation projects, from resource planning and budgeting to stakeholder engagement and technical reporting, demonstrating strong organizational skills and a commitment to high-quality, timely results. My leadership on the GoCAV platform resulted in a fully documented and notarized autonomous vehicle implementation, demonstrating both technical rigor and real-world readiness. I have also formalized five new project concepts based on GoCAV and am eager to advance these through new partnerships and collaborations. Additionally, I contribute to the AUTONAVIS R&D website to share technical achievements and promote opportunities for broader research cooperation.

Beyond implementation, I have played a substantial role in preparing numerous Horizon Europe proposals, contributing to technical sections and, in one case, authoring the complete proposal. My involvement has extended to consortia formation, work package definition, and aligning the technical vision with call objectives.

I have also held key technical management roles, leading multidisciplinary teams and work packages within Horizon Europe, H2020, and national R&D initiatives. Notably, my contribution to the SAFE STRIP project led to the successful granting of a patent, further validating my impact on innovative research outcomes.

Project management has become integral to my professional approach, complementing my technical background and enabling me to deliver complex, multidisciplinary projects with confidence. I am now eager to assume greater responsibilities as an R&D Project Manager within larger international consortia, where I can utilize my experience and leadership skills to drive innovation and deliver impactful results aligned with European research objectives.

CURRICULUM VITAE

CHRISTOS SOUGLES

PERSONAL INFORMATION

DATE OF BIRTH:	25/08/1982
PLACE OF BIRTH:	Thessaloniki, Greece
MARITAL STATUS:	Married
ADDRESS:	Sampsountos 20, Thermi, 57001, Thessaloniki, Greece
CONTACT NUMBERS:	00306972233164, 00302310419369
E-MAIL:	c.sougles@autonavis.com
LinkedIn:	http://lnkd.in/b-CxryD
Website:	https://autonavis.com/

PROJECT MANAGEMENT EXPERIENCE & ACHIEVEMENTS

- Led and coordinated technical work packages (WPs) and deliverables in Horizon Europe, H2020, and national research projects (SAFE STRIP, FLEXIndustries, ODOS 2020, etc.), including:
  - **FLEXIndustries (Horizon Europe):** Technical Manager, WP5 - led the design and deployment of a Decision Support System (DSS) for seven industrial pilot sites; coordinated teams, tracked milestones, reported to project coordinators, and participated in meetings with the European Commission.
  - **AE3vAO (National Project):** Overall Project Management - supervised technical and administrative implementation of an intelligent bin monitoring system; managed coordination, milestone achievement, and reporting.
  - **SAFE STRIP (Horizon Project):** Led architecture and implementation of V2X-enabled roadside units; managed pilot testing, deliverable writing, and compliance with Horizon 2020 standards.
  - **GoCAV Project:** Led the development and deployment of the GoCAV autonomous vehicle platform, overseeing all stages from concept to field validation. Established strategic partnerships, coordinated EU project proposals, managed project timelines, and devised exploitation plans for technology transfer to full-scale electric vehicles.
- Oversaw progress tracking, risk management, and quality assurance for multiple large-scale projects.
- Coordinated international, multidisciplinary teams, organized meetings, prepared reports, and maintained stakeholder communication.
- Contributed to proposal writing, budgeting, and consortium formation for European-funded projects.
- Supported business model development, exploitation, and dissemination (including IPR, commercialization, and technology transfer).
- Mentored junior engineers and onboarded new project partners within multicultural, interdisciplinary environments.

WORK EXPERIENCE

- **February 2021 – Present**

  Worked as Principal Engineer at AUTONAVIS R&D.

  The GoCAV platform is a fully re-engineered autonomous go-kart designed as a modular, real-world research and validation environment for autonomous driving systems. Featuring LiDAR, high-definition camera, advanced AI algorithms, and RTK GPS, GoCAV enables comprehensive testing, bridging the gap between simulation and live operation while prioritizing safety and robustness. The platform has undergone significant evolution through efficiency improvements, CAN network integration, and the development of custom microcontroller firmware. GoCAV continues to serve as a flexible benchmark for field testing and the rapid growth of next-generation autonomous mobility solutions. (Explore GoCAV in Action**:** https://autonavis.com/gocav/)

  Key Contributions:

  - Managed the full development of GoCAV: system architecture design, hardware integration, embedded firmware development, and field testing.
  - Integrated and optimized sensors (LiDAR, camera, RTK GPS) and real-time data processing pipelines for perception and navigation.
  - Designed and implemented safety-focused control strategies to minimize risk during real-world trials.
  - Led the integration of CAN networks and coordinated the development of microcontroller-based control modules.
  - Built collaborative networks with partners in embedded systems, autonomous vehicles, and V2X communications.
  - Authored technical documentation, managed reporting, and ensured proper notarization of project outcomes to facilitate future scaling and seamless integration into new applications.
  - Prepared proposals for European R&D projects, supporting consortium formation and multi-partner collaboration.
  - Initiated plans for transferring GoCAV technology to full-scale electric vehicles, with further applications for accessible mobility and emergency response.

- **January 2023 – December 2024**

  Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" in the Horizon research program FLEXIndustries.

  The FLEXIndustries project focuses on developing and implementing energy efficiency measures and process flexibility methods across seven industrial sectors. It aims to ensure the seamless integration of these solutions with electrical and thermal networks. The project aims to develop a methodology for assessing flexibility in industrial environments and enhance connectivity between the IT and technology sectors within the energy domain. FLEXIndustries will deliver a secure platform for dynamic energy and process management, supporting process flexibility while promoting clustering methods to enhance the local renewable energy capacity and increase industrial flexibility. Additionally, the project will demonstrate and validate its solutions in seven real-world industrial environments, designing sustainable business models to enable the energy transition in energy-intensive industries. FLEXIndustries aims to

improve energy efficiency and enhance flexibility in industries, contributing to more sustainable and efficient energy use.

Key Contributions:

- *Technical management of WP5*
- *Decision Support System (DSS) design for each of the seven pilot trials*

➢ **October 2022 – December 2024**

Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" in the Greek research program AE3vAO.

The AE3vAO project focuses on creating a digital platform for the efficient management and optimal utilization of food waste. Globally, one-third of the food produced is lost or wasted, resulting in inefficient resource utilization and adverse economic and environmental consequences. The project aims to decompose organic matter and enhance biowaste management through the use of innovative technologies, such as intelligent recycling bins.

The project aims to develop an intelligent platform that monitors the filling levels and operational status of anaerobic digestion bins in real-time, while engaging users in rational waste management. The platform will utilize machine learning and deep learning techniques for data analysis and inference. A multi-user recognition system will also be developed, using Bluetooth or NFC tags, to promote personalized usage and track recycling performance.

The platform's architecture is based on a Raspberry Pi microcomputer, which is connected to sensors that monitor the bins. Data is stored in a database and can be accessed via the internet or a mobile app. The project will be validated at key city locations to assess its effectiveness, aiming to promote circular economy practices, reduce costs, and foster ecological awareness.

Key Contributions:

- *Technical management of the bin monitoring system*
- *Overall project management*

➢ **February 2022 – October 2022**

Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" in the Greek research program ΣΕΛΑΣ.

The ΣΕΛΑΣ project aims to study and leverage new photovoltaic system technologies in existing highway infrastructure (e.g., guardrails, toll booth structures, parking areas) to cover part of their energy needs. Its innovative photovoltaic systems generate electricity 24/7, utilizing ambient light from other sources (e.g., car headlights, highway lighting) during nighttime. *(See attached related photographic material – SELAS GREEK PROJECT)*

Key Contributions:

- *Programming, constructing, and installing the pilot system on-site.*
- *System connection to the platform via a 4G/LTE network.*
- *The writing of the project deliverables*

- **October 2021 - October 2022**

  Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" in the Greek research program Renaissance.

  The Renaissance project is an Innovation Action (IA) that provides a community-based, scalable, and replicable approach for implementing new business models and technologies that support clean energy production and shared energy distribution within local communities.

- **May 2021 – October 2021**

  Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" and participated in the Horizon research program IoTAC.

  The IoTAC project aims to provide an innovative, secure, and privacy-friendly architecture for the Internet of Things (IoT) that facilitates the development and operation of more attack-resilient services through (a) monitoring and assessing security throughout the broader lifecycle and development of software, (b) creating an advanced access control mechanism based on an innovative interaction model using integrated cards and private key technology, (c) detailed logging of system execution processes, and (d) providing relevant mechanisms to certify the security of produced applications and systems, based on international security standards, best practices, and the project's research findings.

  The results will be demonstrated by implementing four use cases in IoT environments where fully functional applications will be developed in a laboratory setting. Finally, one of the project's priorities is establishing certification mechanisms in the field of IoT system security.

- **April 2020 – April 2021:**

  Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" and participated in the Greek research project ODOS 2020 (https://odos2020.iti.gr/).

  ODOS 2020 aims to introduce an innovative technological solution that, through the use of the "Internet of Things" (IoT) and infrastructure-to-vehicle communication technologies, implements collaborative applications in the field of Intelligent Transportation Systems without significant or costly interventions on the roadway, significantly contributing to increased road safety and the safe maintenance of infrastructure. The integrated technological solution will be aimed at all types of vehicles (passenger cars, trucks, motorcycles) and will require minimal to no equipment from the vehicles. *(See attached related photographic material – ΟΔΟΣ 2020 GREEK PROJECT)*

  Key Contributions:

  - *The design of the system architecture*
  - *The design and construction of the power supply unit (autonomous system – use of batteries and photovoltaic) for the RSU (Road Side Unit)*
  - *The writing of the project deliverables*

- **May 2020 – April 2021**

  Worked as a Senior Embedded Systems Engineer (Research Associate) at the "Centre for Research & Technology Hellas – Information Technologies Institute" and participated in the European research project EXA2PRO.

The goal of the EXA2PRO project is to develop a programming environment that facilitates the improved development of parallel algorithms for solving complex scientific problems on exascale computing systems (1,018 operations per second). It is expected to support a range of scientific applications by providing programming tools to improve the quality of numerical codes, assist in the more efficient and rational management of the heterogeneous structure of modern computing systems at the hardware level, and provide tools for optimizing memory management.

- **July 2017 – August 2020:**

  Worked as Senior Embedded Systems Engineer (Research Associate) at "Centre for Research & Technology Hellas – Information Technologies Institute". I have participated in the SAFE STRIP European Research Program (http://safestrip.eu/).

  SAFE STRIP aims to introduce a disruptive technology that will enable the embedding of C-ITS applications in existing road infrastructure, including novel I2V (Infrastructure-to-Vehicle) and V2I (Vehicle-to-Infrastructure) functions, as well as VMS (Variable Message Sign) and VSL (Variable Speed Limit) functions, into low-cost, integrated strip markers on the road. *(See attached related photographic material – SAFESTRIP HORIZON PROJECT)*

  Key Contributions:

  - *The design of the system architecture*
  - *The operation of the RSU (Road Side Unit)*
  - *The implementation of communication protocols ITS-G5, LTE, BLE*
  - *The PCB design of the RSU (Road Side Unit)*
  - *The operation and installation of the RSU on the road during pilot tests*
  - *The writing of the project deliverables*

- **June 2015 – June 2017:**

  Worked as Embedded Systems Engineer (Research Associate) at "Centre for Research & Technology Hellas – Information Technologies Institute". I have participated mainly in a European Research Program (My Air Coach) and other Research Programs by supporting Embedded Systems Development.

  Key Contributions:

  - *Writing Firmware (Embedded C Programming) for TI Microcontroller MSP430 (My Air Coach Project)*
  - *Designing SAFE STRIP Project Specifications (Project Proposal)*
  - *Electronic Circuit Designing – Schematic & PCB – (WATT+VOLT "1-phase" & "3-phases" Energy Meters)*
  - *Object Oriented C++ Programming*
  - *Database Designing*
  - *System Integration*

➢ **January 2015 - August 2015:**

Worked as an Embedded Systems Engineer (self-employed). The project aims to build my libraries for peripheral devices using the Atmel microcontroller 89C51AC2.

The project objectives are the following:

- *The building of a circuit that is composed of:*
  - *Atmel microcontroller 89C51AC2*
  - *Graphical LCD (240 x 128)*
  - *Keypad (4 x 4)*
  - *4 external 8Kb RAMs*
  - *RS-232 DE9 connector*
- *The firmware development to enable the following functionalities:*
  - *Data display in the Graphical LCD (240 x 128) (graphics and text)*
  - *Data input in the Graphical LCD by using the keypad*
  - *Data recording in the 4 external 8 Kbytes of RAMs (data coming from the microcontroller serial port or future sensors connected to the microcontroller input pins)*

The circuit has been designed to facilitate future expansion. Especially, the following inputs & outputs are available:

- *8 digital inputs*
- *8 digital outputs*
- *8 analog pins, either used as inputs or outputs (port P1 special functions)*
- *External Interrupt 0 & 1 Inputs (Port P3 special functions)*
- *Timer 0 & 1 Counter Inputs (Port P3 special functions)*

(See attached related photographic material – ATMEL MICROCONTROLLER 89C51AC2 & PERIPHERAL DEVICES)

➢ **November 2012 - October 2013:**

Worked as Technical Manager (Supervisor of the Installation and Maintenance of the automated bike sharing–parking system) at “Brainbox Informatics” company.

Key Contributions:

- Managing the purchase of tools and spare parts required for installation and maintenance
- Overseeing the installation process of the automated bike-sharing and parking system
- Conducting technical training sessions and supervising system installers across various cities.
- System maintenance:
  - Providing remote technical assistance to local technicians
  - Maintaining comprehensive technical records of the system’s performance in each city
  - Resolving major technical issues on-site

- Proposing and submitting system improvement suggestions to the Dutch supplier

Different system versions have been installed in the following Greek cities.

- *Automated Bike Sharing system in the municipalities of*
  - *Ioannina - 10 bikes / 2 stations*
  - *Didymoteicho - 100 bikes / 7 stations*
  - *Komotini - 100 bikes / 6 stations*
  - *Kavala - 50 bikes / 4 stations*
  - *Karditsa - 70 bikes / 6 stations*
  - *Keratsini - Drapetsona - 70 bikes / 6 stations*
  - *Nafpaktos - 60 bikes / 4 stations*
- *Automated Bike Sharing system "Thessbike" 6 bikes / 1 station in Thessaloniki*

Automated Bike Parking system OTE – COSMOTE 80 automated bike parking locks in high-traffic spots in Athens (Golden Hall, The Mall Athens, Floisvos Marina, Plazza Mall, etc).

(See attached related photographic material – AUTOMATED BIKE SHARING & PARKING SYSTEM).

- **February 2010 – November 2010:**
  Joined the army. I served in the Technical Corps.

- **September 2007 - August 2008:**
  Worked as an Embedded Systems Engineer. I implemented a remote temperature monitoring system for industrial refrigerators (Telemetry System) during the project.

  The primary objective of this project was to develop a remote monitoring system for the temperature of industrial refrigerators using the RS485 network, a Wavecom GSM modem, and Atmel T89C51AC2 microcontrollers.

  During the implementation, I designed and built the control device for the GSM modem, which served as the master device, and monitoring devices for the refrigerators, which acted as slave devices supporting up to nine units. Additionally, I developed the firmware for all devices, ensuring their functionality. The master and slave devices were equipped with backup power supplies using rechargeable batteries, ensuring reliable operation even during power interruptions.

  Communication between the master and slave devices was established via the wired RS485 network. Since the RS485 network lacks a data link layer, I designed and implemented a custom data link layer to facilitate seamless communication. Interaction between the user and the GSM modem, controlled by the master device, was enabled through bidirectional text messages (SMS). The system could notify users about critical events, such as alarm activations or power failures affecting one or more refrigerators. Furthermore, users could query the operating status of specific refrigerators at any time by sending an SMS to the system, which recognized a unique format for such requests.

  The master and slave devices were designed to allow the configuration of their operating parameters, including the number of users. This configuration could be performed by both the

installation engineer and the user through a built-in keypad on each device. This flexibility ensured the system could be tailored to meet the specific requirements of different installations. (See attached related photographic material – TELEMETRY SYSTEM)

- **April 2006 - September 2006:**
  Worked as an Automation Engineer at the company “Digintel”.

  Key Contributions:

  - Elevator Floor Indicator Lights Controller - Programmed a microcontroller (ATtiny13 - AVR) to control the floor indicator lights of an elevator system.
  - The implementation of a remote watering system supervisor:

    The project's primary objective was to design, construct, and program a remote supervision device utilizing an ATmega32 microcontroller for a watering system. The watering system consists of a wheel with a coiled hose and a tractor that drives the wheel. To initiate watering, the user unrolls the hose using the tractor, which then slowly recoils the hose after use. The supervision device was designed to adapt to the wheel and provide the user with critical information, including the remaining length of the hose until it is fully recoiled, the estimated time until the watering process is completed, and the instantaneous velocity of the watering operation.

    During the project, I designed and constructed the printed circuit for the supervision device and developed its firmware. The firmware facilitated communication between the user and the GSM modem integrated into the device. The interaction was enabled through a missed call initiated by the user, to which the supervision device responded with an SMS containing the requested information. The system was designed to accommodate one user at a time, with the user's mobile number set during the device configuration procedure.

    The configuration procedure involved setting several parameters using an embedded keyboard, allowing the installation engineer and the user to tailor the system to their needs.

  - *The design (Vision) and the building of the electrological panel of a machine that stretches a painting canvas. Moreover, I programmed the Programmable Logic Controller (PLC), which is the fundamental element of the entire system.*
    (See attached related photographic material - CANVAS STRETCHING MACHINE FOR PAINTING FRAMES)

PATENTS

- **Collaborative Non-Invasive Road Safety Layout for Smart Road Infrastructures**
  Greek Patent No. 1010371, Issued Jan 16, 2023
  (ΣΥΝΕΡΓΑΤΙΚΗ ΜΗ ΠΑΡΕΜΒΑΤΙΚΗ ΔΙΑΤΑΞΗ ΟΔΙΚΗΣ ΑΣΦΑΛΕΙΑΣ ΓΙΑ ΕΥΦΥΕΙΣ ΟΔΙΚΕΣ ΥΠΟΔΟΜΕΣ)

  This invention introduces a groundbreaking, low-cost, and energy-independent technology for road safety enhancement on motorways, without the need for extensive modifications to the road surface. It features a modular pavement layout with encapsulated sensors, communication units, and energy elements, as well as an auxiliary communication portal equipped with advanced wireless connectivity (BLE, LTE, ITS-G5). I focused on the construction, installation, and validation of the auxiliary communication portal, contributing to the system's deployment and validation.

PUBLICATIONS

- **A. Dimara, C. Sougles, S. Athanasiou, K. Grigoropoulos, P. Sfakianou, A. Papaioannou, S. Krinidis, D. Triantafyllidis, I. Tzitzios, C. N. Anagnostopoulos, A. Karamanidis, V. Saltagianni, D. Ioannidis, D. Tzovaras,** "*Holistic plug-n-play autonomous solar system integration: a real-life small-scale demonstration—a practical approach.*", Electr Eng 105, 2715–2733 (2023). https://doi.org/10.1007/s00202-023-01830-6

- **A. Lalas, S. Nousias, D. Kikidis, A. Lalos, G. Arvanitis, C. Sougles, K. Moustakas, K. Votis, S. Verbanck, O. Usmani, D. Tzovaras,** "*Substance deposition assessment in obstructed pulmonary system through numerical characterization of airflow and inhaled particles attributes*", BMC Medical Informatics and Decision Making, 17 (Suppl 3): 173, 2017. [doi: 10.1186/s12911-017-0561-y]

CERTIFICATIONS & TRAINING

- **The Complete Self-Driving Car Course – Applied Deep Learning**

  Udemy, April 2024

  (18 total hours; instructors: Rayan Slim, Amer Abdulkader, Jad Slim, Sarmad Tanveer)

  Covered advanced topics in neural networks, computer vision, and AI for autonomous vehicles with hands-on projects.

EDUCATION

- **Graduated in October of 2009:** University of Bristol, UK, MSc in Advanced Microelectronic Systems Engineering (scholar)

  DISSERTATION
  "Controller Area Network – Performance and Traffic Management"

  The primary objective of this project was to evaluate the performance of two types of CAN networks: Event-Triggered CAN (ETCAN) and Time-Triggered CAN (TTCAN). We implemented various data transmission scenarios under different bus loads in a CAN network to achieve this. The network setup consisted of two LPC2378 microcontrollers and a CAN analyzer, which generated traffic and measured message transmission times.

  Upon completing the project, we observed that the response time for an asynchronous external event in ETCAN is influenced by message priorities and the sequence in which the messages are transmitted on the bus. In contrast, the performance of TTCAN remains unaffected mainly by bus load, relying instead on the structure of the matrix cycle.

  A noteworthy finding emerged from the analysis of transmission times between the two microcontrollers: the accuracy of measuring transmission times directly on the microcontrollers is not only comparable to the results from the CAN analyzer but, in some cases, can even surpass it. This result highlights a significant advantage, especially considering the high cost of the CAN analyzer.
  (See attached related photographic material – BRISTOL DISSERTATION)

- **Graduated in June of 2007:** Alexandreio Technological Educational Institute of Thessaloniki, Greece, Degree in Automation (Highest Grade Point Average)

  THESIS
  "Telemetry through 8051 and GSM / GPRS Modem"

  The primary objective of this project was to design, build, and program a remote control device using the Atmel AT89C51AC2 microcontroller. The device could control eight digital outputs, providing the system user with real-time updates on the status of eight digital inputs and notifying them in the event of a system alarm.

  As part of the project implementation, I designed and constructed the circuit board for the remote-control device. Additionally, I developed the device's firmware, enabling communication between the user and a GSM modem via bidirectional text messages (SMS). The device recognized a unique SMS format for interaction. Only one system user could be configured at a time, with their mobile number defined during the device's setup process.

  This system, developed as part of my thesis, was showcased at the 21st International Technology, Telecommunications, and Digital Technology Exhibition in Thessaloniki in October 2007.
  (See attached related photographic material – AUTOMATION THESIS)

SOFTWARE - HARDWARE KNOWLEDGE & SKILLS

- **Software (Applications & Tools):**

  Visio, Altium, Corel, Proteus (Professional 7), Cadence, Wireshark, MS Office, Windows, AutoCAD (basic), Linux (Debian/Ubuntu/Raspberry Pi OS)

- **Software (Programming):**

  Assembly, Embedded C, Object-Oriented C++, Python, Linux Shell Scripting, Verilog, VHDL

- **Hardware (Microcontrollers):**

  - **Programmed in C:**
    - ***AVR:*** ATtiny13, ATmega 8/16/32/328P
    - ***NXP (PHILIPS):*** LPC2378
    - ***MOTOROLA:*** 68HC12
    - ***TI:*** MSP430F5438A

  - **Programmed in C & Assembly:**
    - ***ATMEL:*** AT89C51RD2, AT89C51AC2, AT89C51CC03

- **Hardware (Development Boards)**
  - Raspberry Pi 5
  - Arduino Nano και Mega V3.0
  - i.MX 7Dual SABRE (MCIMX7SABRE) - NXP Semiconductors

- **Hardware (FPGA):**

  - **Programmed in VHDL (*Basic Knowledge*):**
    - ***MicroBlaze Development Board:*** Kit Spartan-3E 1600E

- **Communication Protocols:**

  - ITS-G5, LTE, BLE, CAN, RS-485, GSM

- **Designing Embedded Systems User Interface**

- **PCB Construction:**

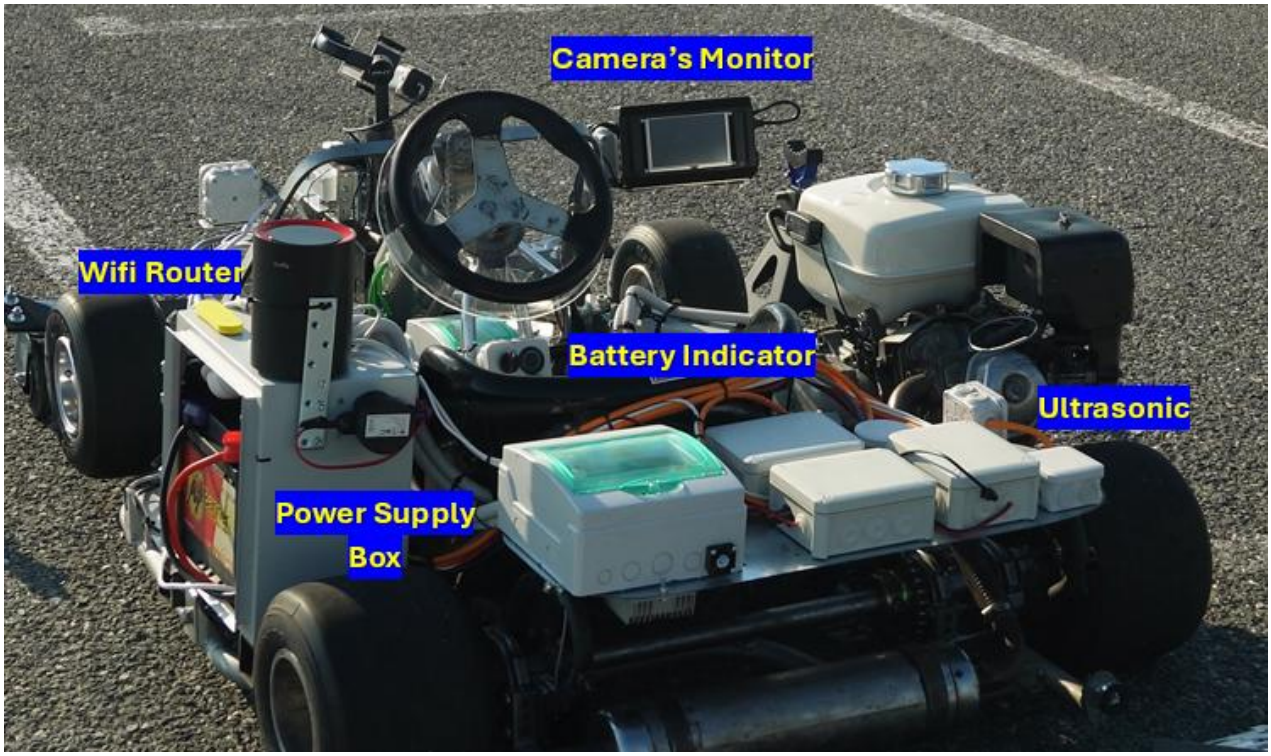
  - UV Exposure and Etching Devices

- **Hardware Tools**
  - CAN-Bus Analyzer

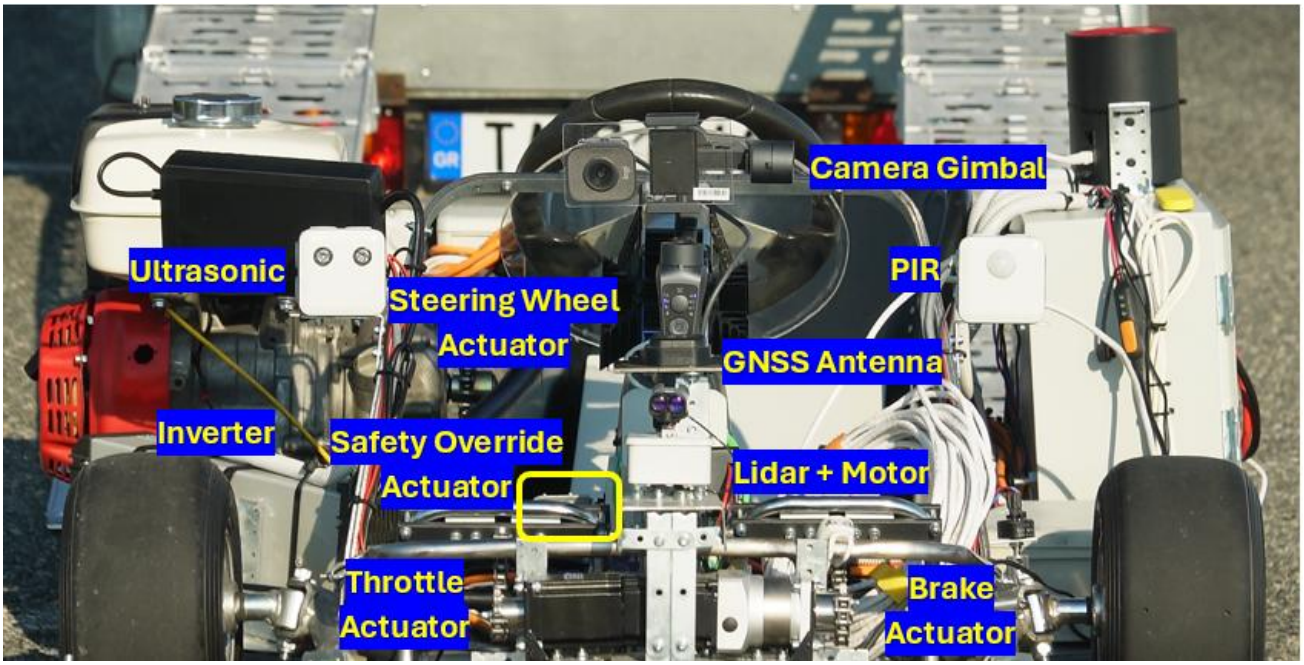
LANGUAGES

- **English:**
  - IELTS (July 2008): Reading 7.5, Listening 6.5, Writing 6.5, Speaking 6
  - MSc studies in the UK (University of Bristol, 2008 - 2009)
  - Daily use in both professional (Horizon Europe and international projects) and personal life (family communication)
- **Greek:**
  - Native speaker

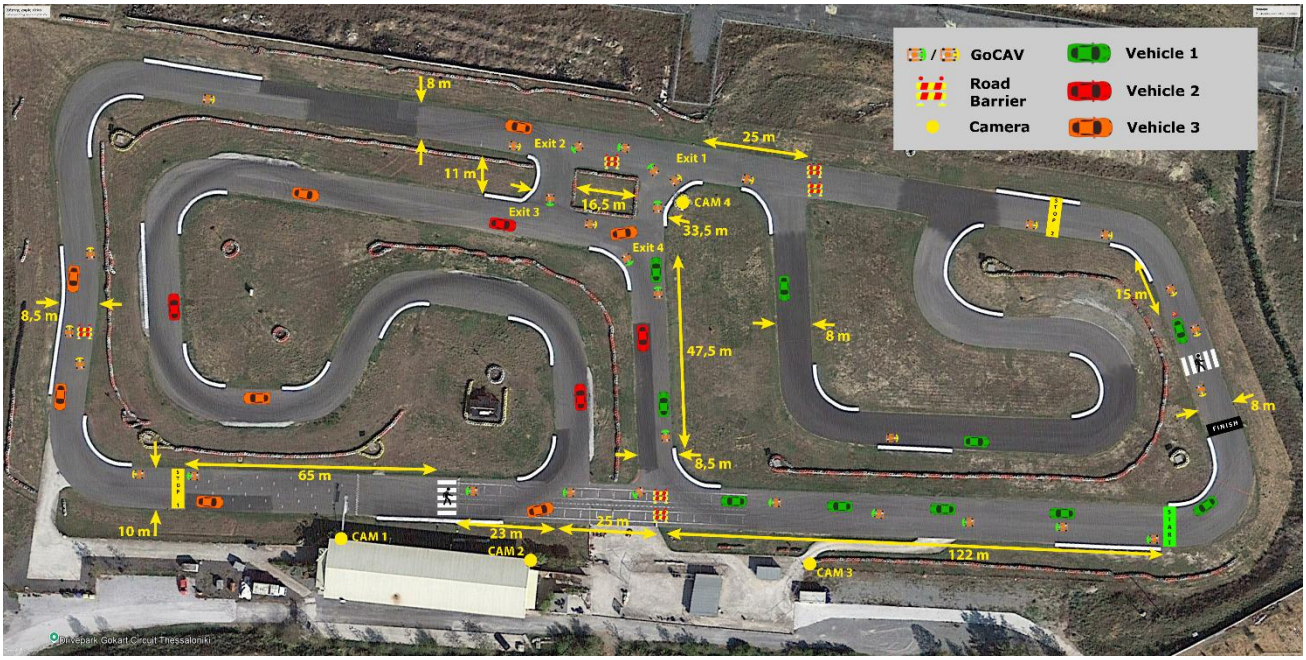
GoCAV PROJECT



GoCAV Rear View

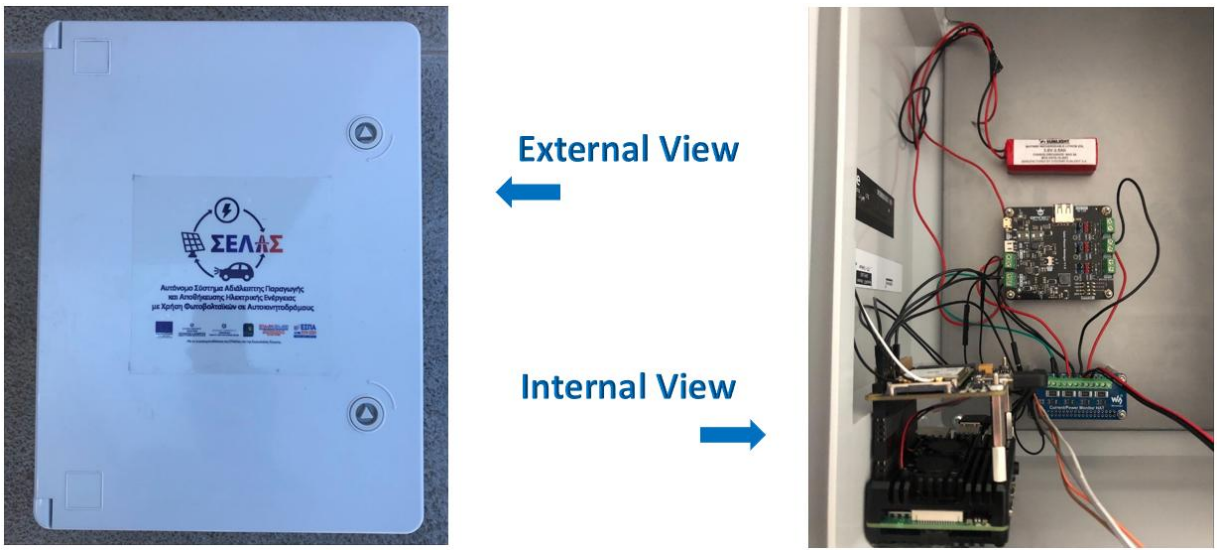


GoCAV Front View



GoCAV Basic Evaluation Scenarios – Drive Park Test Track Layout

ΣΕΛΑΣ
GREEK PROJECT



Under Construction Control Panel for DSSC Photovoltaics

Control Panel of DSSC Photovoltaics – Laboratory Tests

DSSC PV - Night Operation of the System

Conventional PV System Installation

DSSC PV System Installation

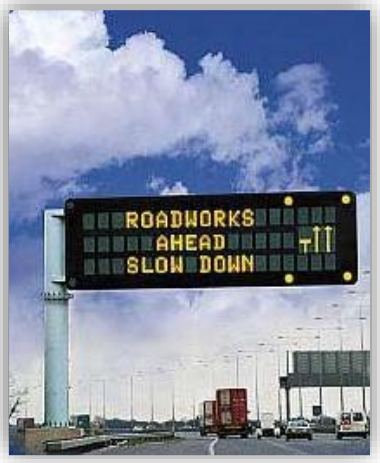
ΟΔΟΣ 2020
GREEK PROJECT

RSU Power Supply Control Panel

SAFE STRIP
HORIZON PROJECT

EXISTING TECHNOLOGY

Information Provided to Vehicles by Road Infrastructure



SAFE STRIP Proposal

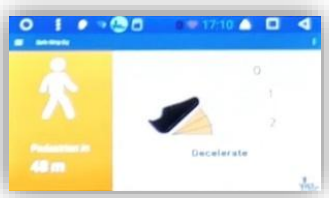
Installation

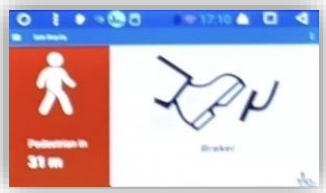
- Reduces the size and cost of the infrastructure
- Reduces installation time
- The system can be installed on the existing road infrastructure

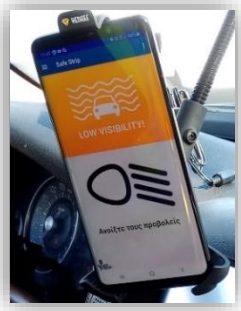
System Operation

- Information is provided by sensors located on the roadway

- Personalized messages (on the vehicle's screen or mobile device) based on the vehicle's position on the roadway



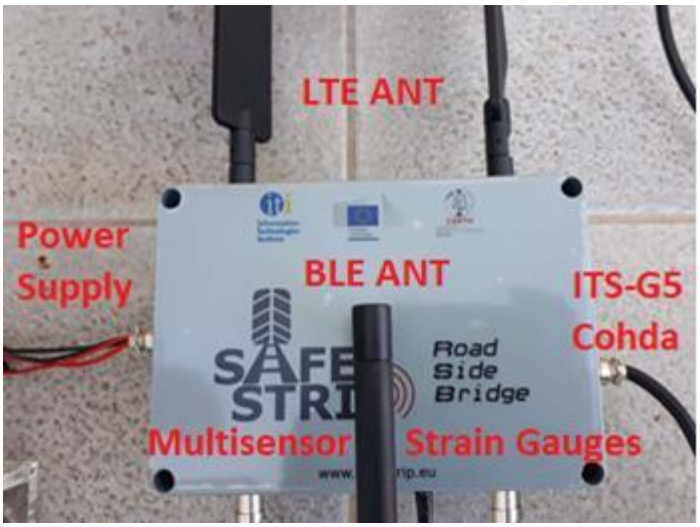




Scenarios Implemented

- Notification about the presence of a pedestrian on the roadway
- Notification about current road surface conditions
- Notification about road surface wear
- Notification about a vehicle moving in the opposite direction of traffic
- Notification about a stationary vehicle on the road due to a breakdown
- Notification about low visibility conditions
- Notification about ongoing roadworks
- Collision avoidance at intersections
- Notification about the presence of an unguarded railway crossing
- Transmission of information to autonomous vehicles
- Notification about approaching an area with virtual tolls
- Parking space management

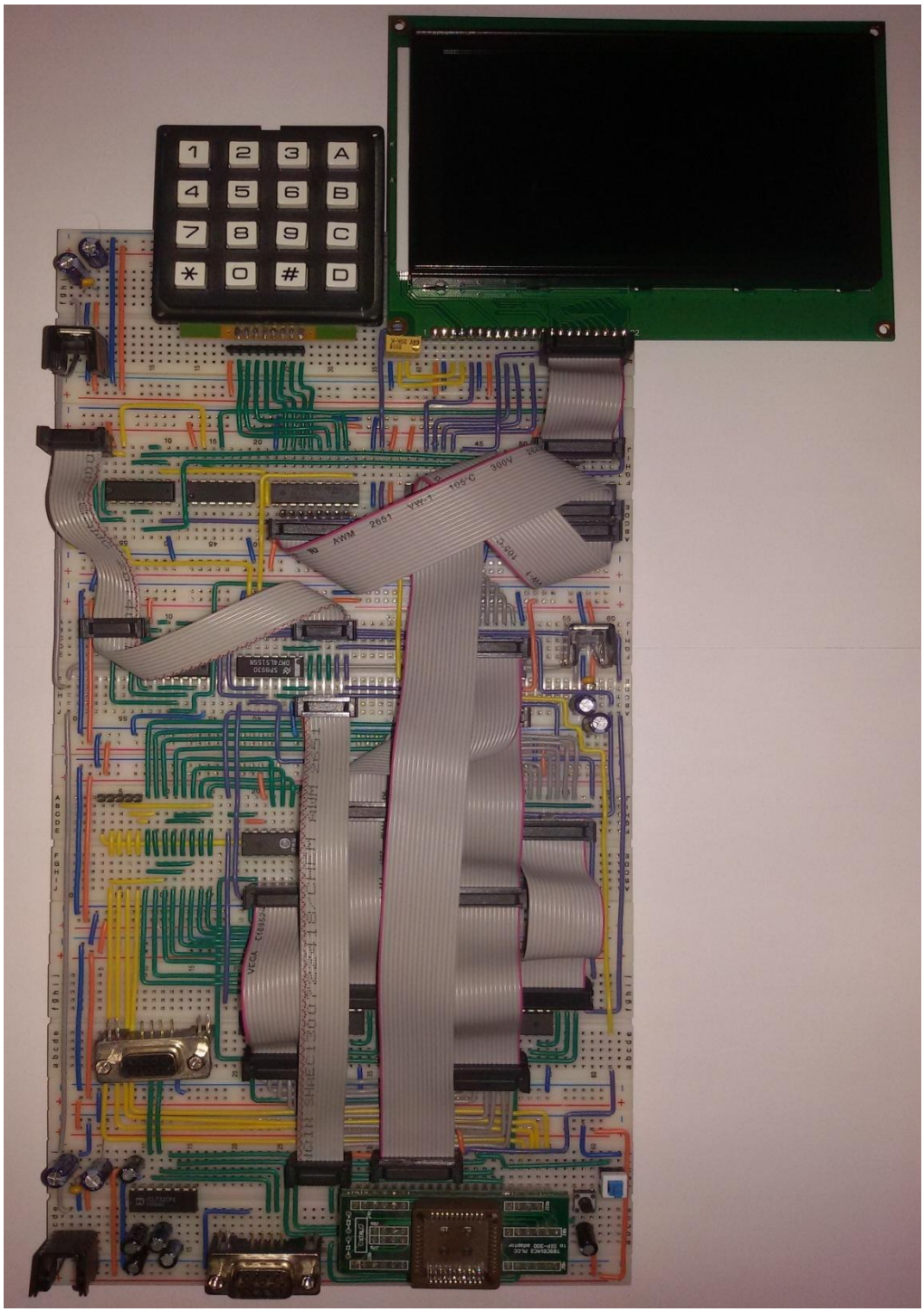
RSB Components



RSB Central Control Unit

RSB Operational Test

ATMEL MICROCONTROLLER 89C51AC2 & Peripheral Devices



Development Board

AUTOMATED BIKE SHARING & PARKING SYSTEM

Automated Bicycle Rental System of Ioannina

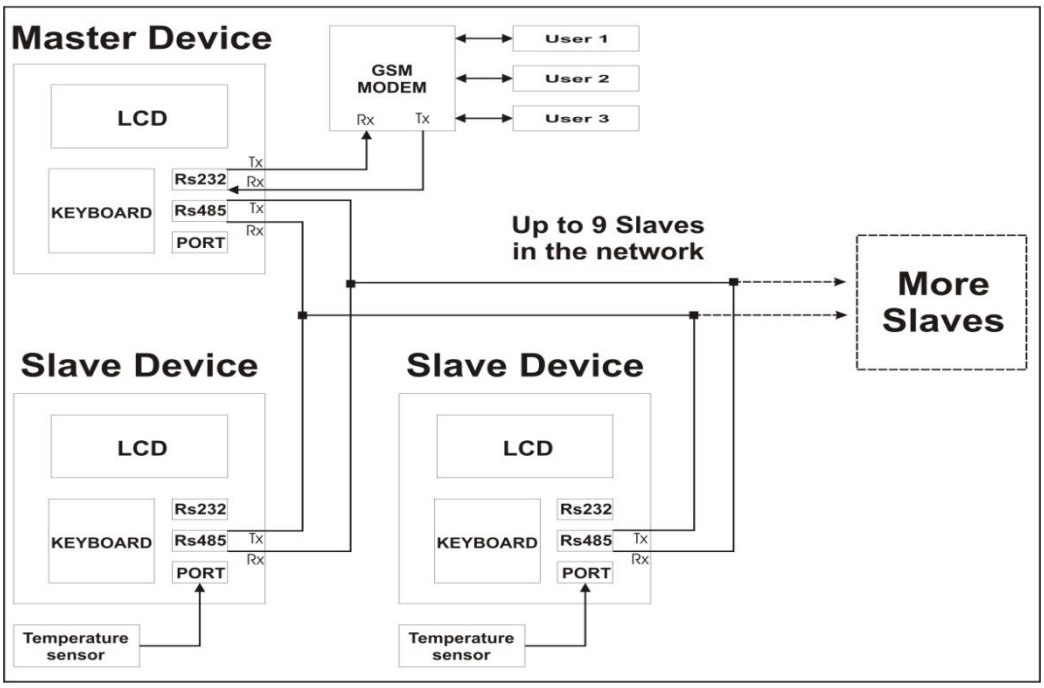
Automated Bicycle Rental System of Didymoteicho

Automated Bicycle Rental System of Karditsa

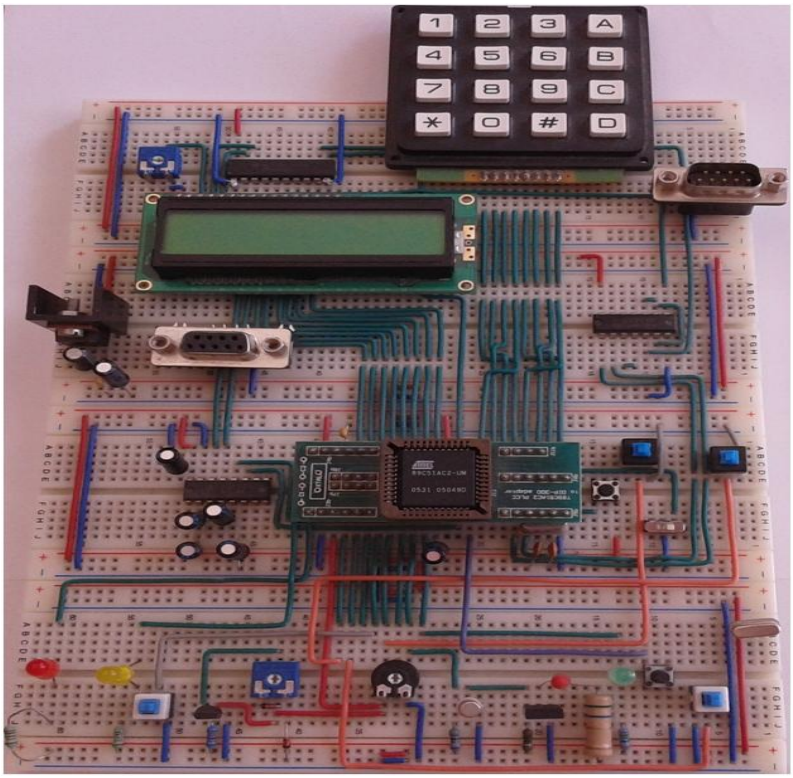
Automated Bicycle Rental System of Karditsa

Automated Bicycle Rental System of Thessaloniki

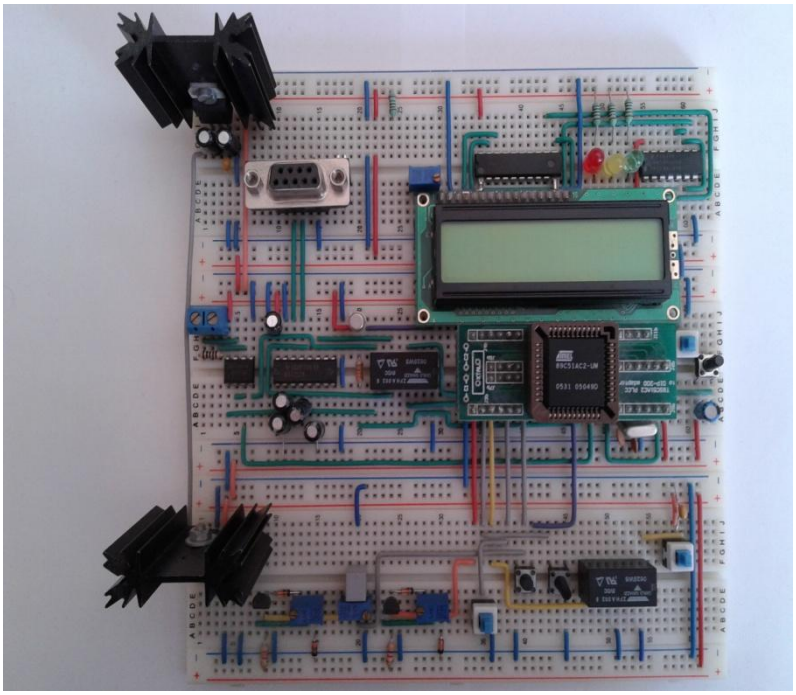
TELEMETRY SYSTEM



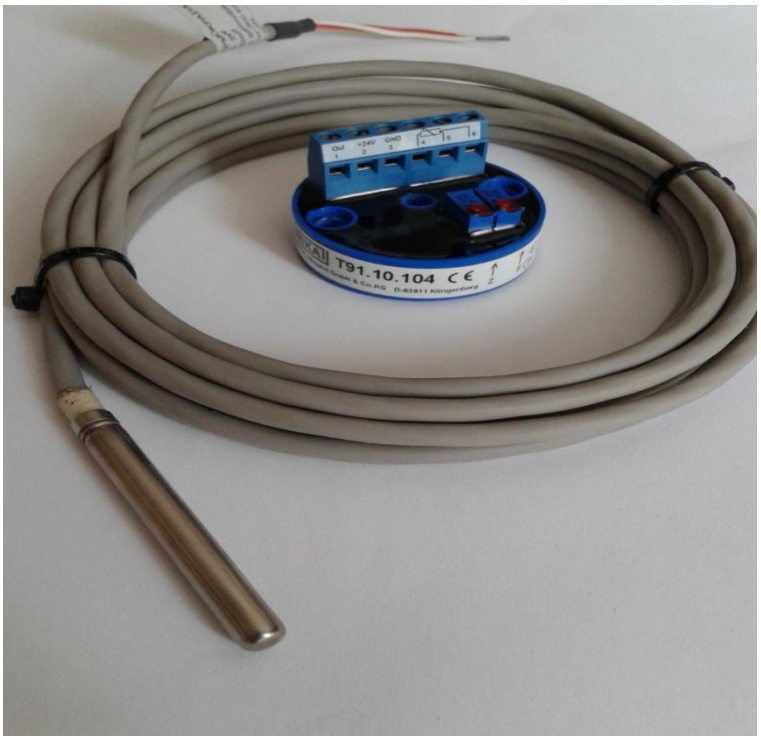
System Architecture



Development Board 1

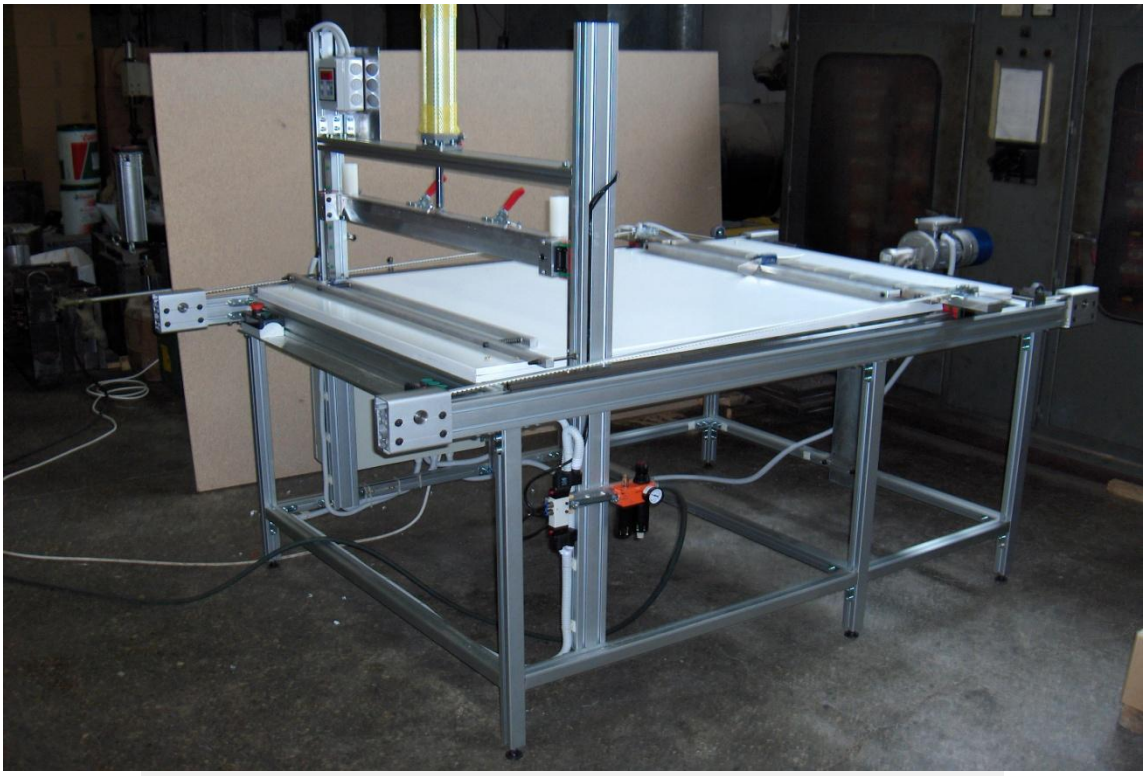


Development Board 2

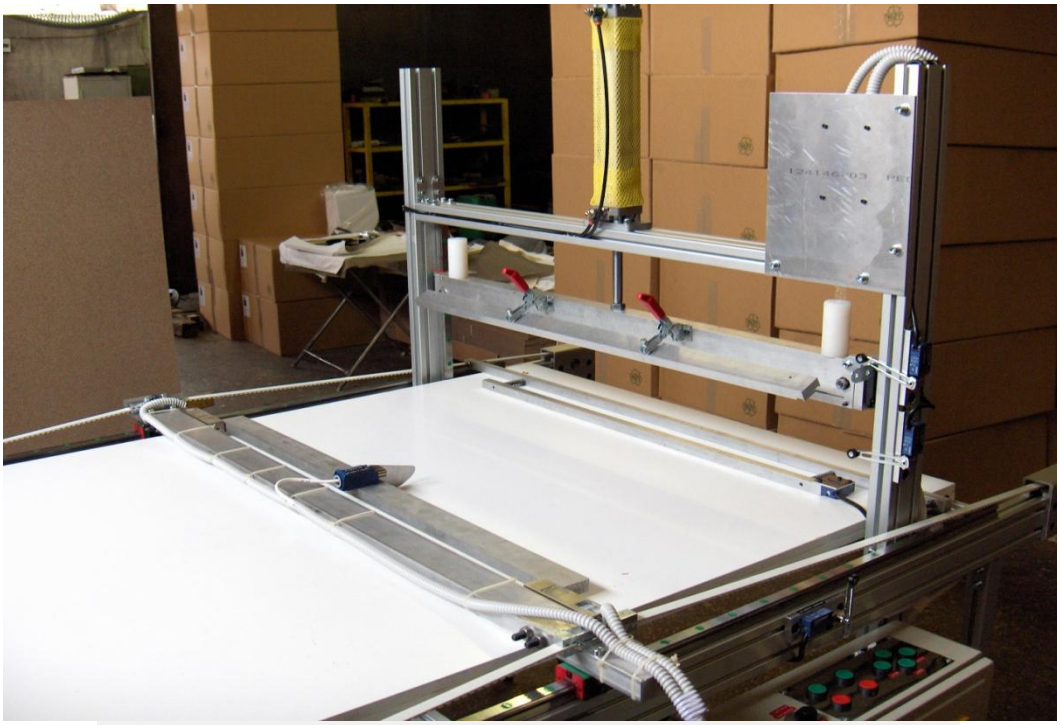


Analog Temperature Transmitter and Temperature Sensor

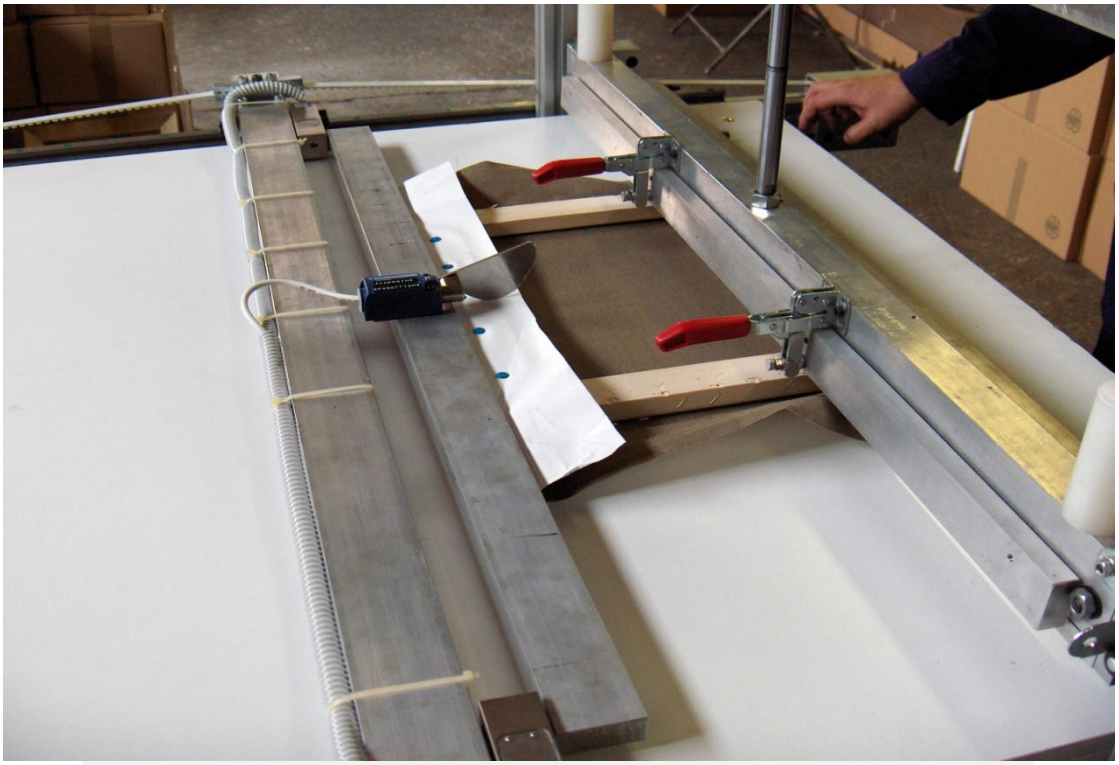
CANVAS STRETCHING MACHINE FOR PAINTING FRAMES



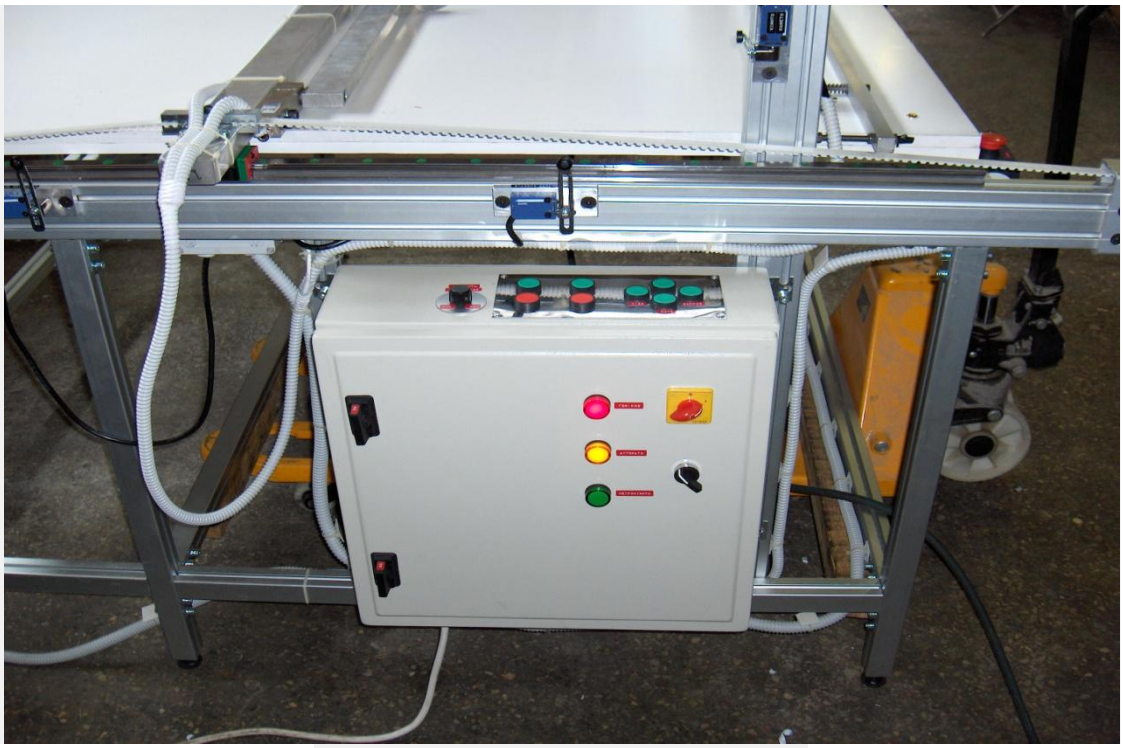
Canvas Stretching Machine for Painting Frames – View 1



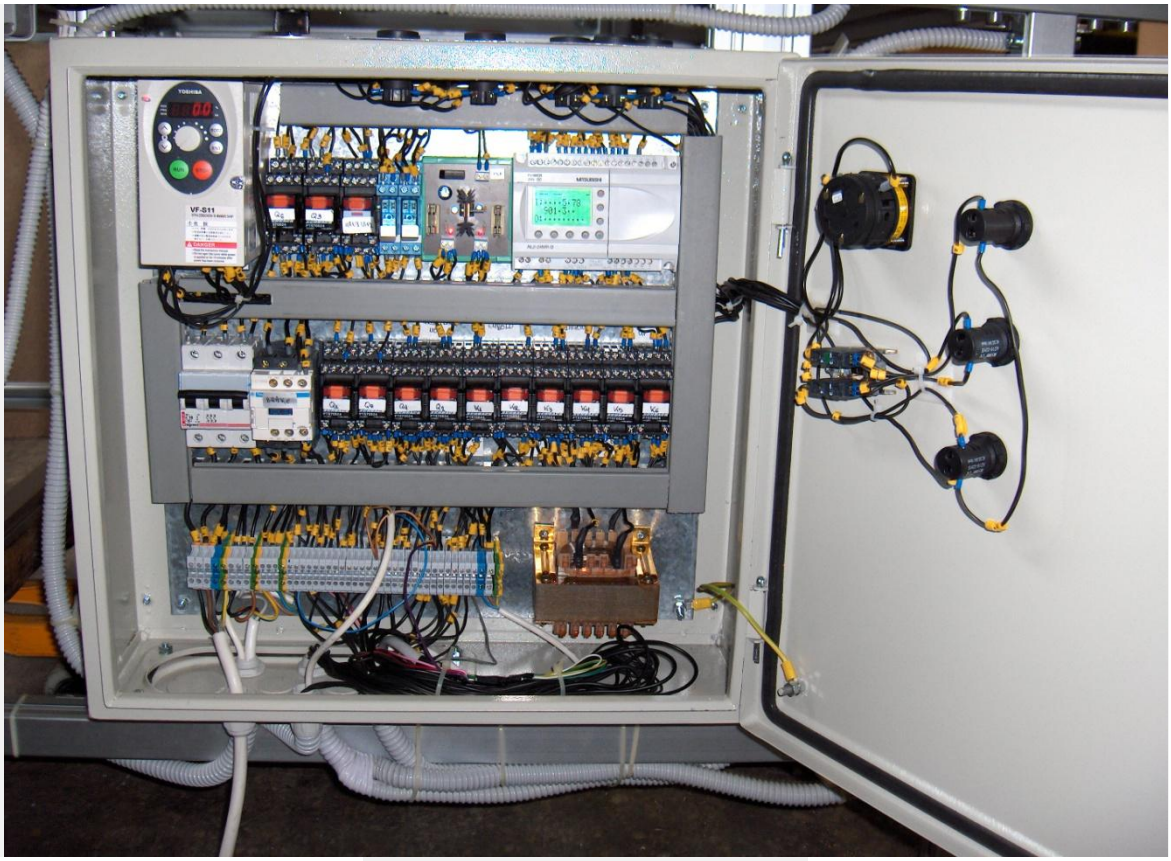
Canvas Stretching Machine for Painting Frames – View 2



Canvas Stretching Machine for Painting Frames – In Operation



External View of Electrical Panel



Electrical Panel Construction

BRISTOL DISSERTATION

IAR LPC2378-SK Development Board

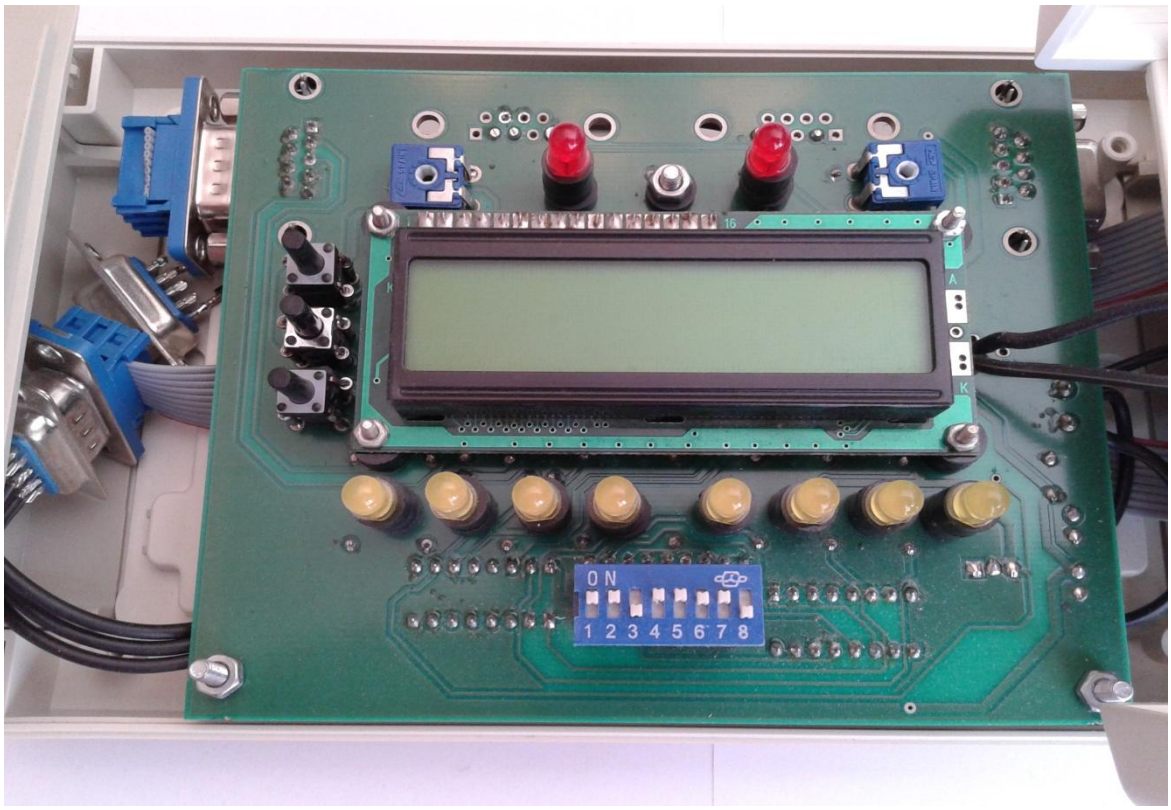
CAN Analyser

AUTOMATION THESIS

Remote Control Device - Front View

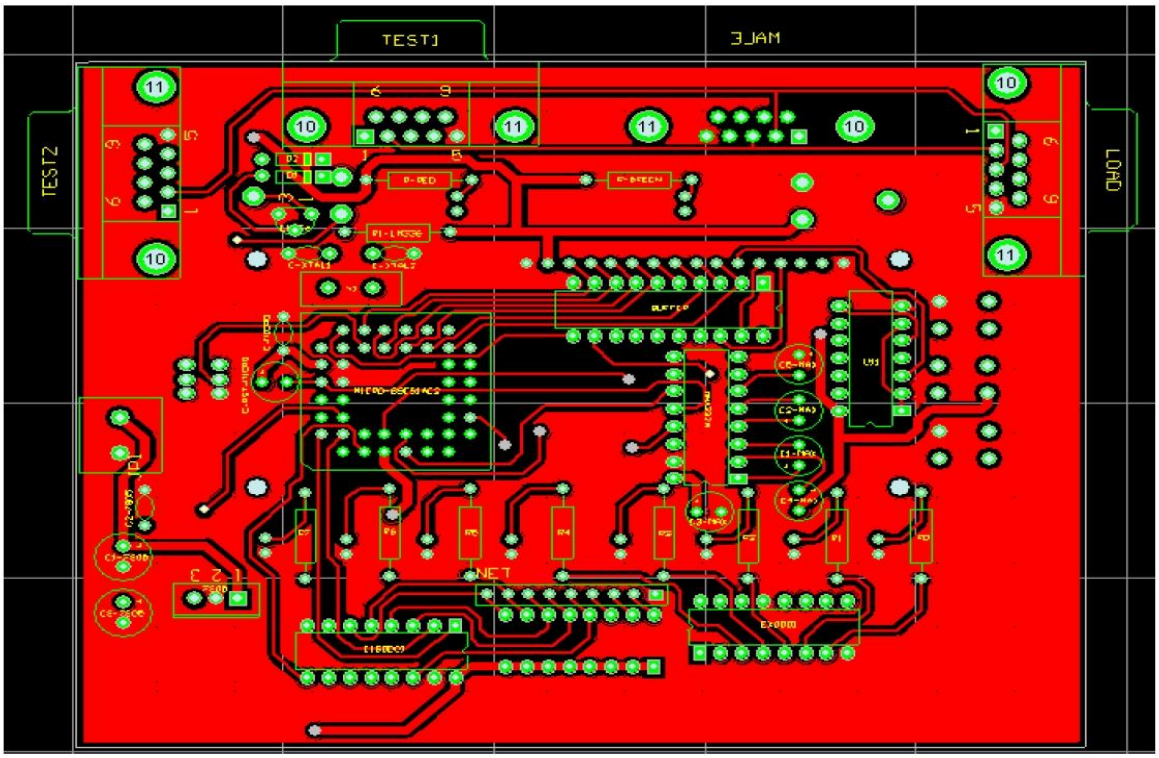
Remote Control Device - Side View

GSM MODEM



Remote Control Device PCB

A. PCB (TOP LAYER)



B. PCB (BOTTOM LAYER)